

Singularly perturbed systems and Tikhonov's theorem

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Perturbation problems

- Suppose that we have a set of equations containing two small parameters, ϵ and δ :

$$\begin{aligned}\frac{dx}{dt} &= f(x, y) + \delta g(x, y) \\ \epsilon \frac{dy}{dt} &= h(x, y)\end{aligned}$$

- If setting one of these parameters to zero gives us a problem we can solve, we have a **perturbation** problem, in which we try to use the known solution as a starting point for developing an approximate solution for small values of ϵ or δ .

Regular and singular perturbations

$$\begin{aligned}\frac{dx}{dt} &= f(x, y) + \delta g(x, y) \\ \epsilon \frac{dy}{dt} &= h(x, y)\end{aligned}$$

- Setting $\delta = 0$ does not change the nature of the equations:
We still have two differential equations.
We call the perturbation problem associated with δ a **regular** perturbation problem.
- Setting $\epsilon = 0$ changes the nature of the equations as the second differential equation is replaced by the algebraic equation $h(x, y) = 0$.
We call the perturbation problem associated with ϵ a **singular** perturbation problem.

Systems associated with a singular system

Given a system in singular perturbation form

$$\begin{aligned}\frac{dx}{dt} &= \mathbf{f}(\mathbf{x}, \mathbf{z}), \\ \epsilon \frac{dz}{dt} &= \mathbf{g}(\mathbf{x}, \mathbf{z})\end{aligned}$$

we define

- The **degenerate system**

$$\begin{aligned}\frac{dx}{dt} &= \mathbf{f}(\mathbf{x}, \mathbf{z}), \\ \mathbf{z} &= \phi(\mathbf{x})\end{aligned}$$

where $\mathbf{z} = \phi(\mathbf{x})$ is the solution of the equation $\mathbf{g}(\mathbf{x}, \mathbf{z}) = \mathbf{0}$.

- The **adjointed system**

$$\frac{dz}{dt} = \mathbf{g}(\mathbf{x}, \mathbf{z})$$

in which \mathbf{x} is treated as a constant.

Tikhonov's theorem

When $\epsilon \rightarrow 0$, the solution of the system

$$\begin{aligned}\frac{d\mathbf{x}}{dt} &= \mathbf{f}(\mathbf{x}, \mathbf{z}), \\ \epsilon \frac{d\mathbf{z}}{dt} &= \mathbf{g}(\mathbf{x}, \mathbf{z})\end{aligned}$$

tends to the solution of the corresponding degenerate system provided $\mathbf{z} = \phi(\mathbf{x})$ is a stable solution of the adjoined system.