

# The particle in a box and the uncertainty principle

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We start by defining the wavefunction. It depends on three "variables", namely the quantum number  $n$ , the length of the box  $L$  and the position  $x$ .

```
> psi := (n,L,x) -> sqrt(2/L)*sin(n*Pi*x/L);
```

$$\psi := (n, L, x) \rightarrow \sqrt{\frac{2}{L}} \sin\left(\frac{n \pi x}{L}\right)$$

The uncertainty principle says that  $\Delta x \Delta p \geq (\hbar)/2$ .  $\Delta x$  and  $\Delta p$  are calculated from  $\langle x \rangle$ ,  $\langle x^2 \rangle$ , etc. I'll start by calculating the average  $x$ , which is found by evaluating the integral

```
> Int(psi(1,L,x)*x*psi(1,L,x), x=0..L);
```

$$\int_0^L \frac{2 \sin\left(\frac{\pi x}{L}\right)^2 x}{L} dx$$

```
> avg_x := value(%);
```

$$avg\_x := \frac{L}{2}$$

Note that I carried out the integration in two steps using the inert "Int" so that you could see the integral being evaluated before we actually obtained a value. Normally, you would just use "int" and get the answer right away. Also, I inserted the value  $n=1$  into the wavefunction through the argument of the Maple function I created.

The answer we get makes perfect sense: The average  $x$  is in the middle of the box.

Now let's calculate  $\langle x^2 \rangle$ :

```
> Int(psi(1,L,x)*x^2*psi(1,L,x), x=0..L);
```

$$\int_0^L \frac{2 \sin\left(\frac{\pi x}{L}\right)^2 x^2}{L} dx$$

```
> avg_x2 := value(%);
```

$$avg\_x2 := \frac{(-3 + 2 \pi^2) L^2}{6 \pi^2}$$

The average of  $p$  and of  $p^2$  are a little more complicated to evaluate since  $p = -i(\hbar\hbarbar)d/dx$ :

```
> Int(psi(1,L,x)*(-I)*hbar*diff(psi(1,L,x),x),x=0..L);
```

$$\int_0^L \frac{-2 I \sin\left(\frac{\pi x}{L}\right) hbar \cos\left(\frac{\pi x}{L}\right) \pi}{L^2} dx$$

Note carefully how I entered this expression in Maple.

```
> avg_p := value(%);
```

$$avg\_p := 0$$

...another common-sense value.

The operator  $p^2 = -(\hbar\hbarbar)^2 d^2/dx^2$ , so  $\langle p^2 \rangle$  is

```
> Int(psi(1,L,x)*(-hbar^2)*diff(psi(1,L,x),x$2),x=0..L);
```

$$\int_0^L \frac{2 \sin\left(\frac{\pi x}{L}\right)^2 hbar^2 \pi^2}{L^3} dx$$

```
> avg_p2 := value(%);
```

$$avg\_p2 := \frac{\pi^2 hbar^2}{L^2}$$

Now to calculate the standard deviations:

```
> Delta_x := sqrt(avg_x2-avg_x^2);
```

$$Delta\_x := \frac{\sqrt{\frac{6(-3+2\pi^2)L^2}{\pi^2} - 9L^2}}{6}$$

This will simplify if we inform Maple that  $L$  is positive.

```
> assume(L>0);
```

```
> Delta_x := simplify(Delta_x);
```

$$Delta\_x := \frac{\sqrt{3} L \sqrt{-6 + \pi^2}}{6 \pi}$$

```
> Delta_p := sqrt(avg_p2-avg_p^2);
```

$$Delta\_p := \frac{\pi \sqrt{hbar^2}}{L}$$

Again, Maple needs to know that  $\hbar\hbarbar$  is positive to simplify this expression:

```
> assume(hbar>0);
```

```
> Delta_p := simplify(Delta_p);
```

```

[

$$\Delta p := \frac{\pi \hbar}{L}$$

[ The uncertainty product is
[ > Delta_x*Delta_p;
[

$$\frac{\sqrt{3} \sqrt{-6 + \pi^2} \hbar}{6}$$

[ > evalf(%);
[

$$0.5678618088 \hbar$$

[ which is bigger than (hbar)/2, as Heisenberg told us it should be.

```