

# Ratner's Theorems on Unipotent Flows

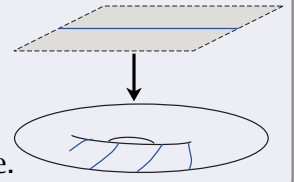
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## Elementary example

Let  $M = \text{torus } \mathbb{T}^2 = \mathbb{R}^2 / \mathbb{Z}^2$

- covering map  $f: \mathbb{R}^2 \rightarrow M$
- $L = \text{line in } \mathbb{R}^2$ .



If the slope of  $L$  is irrational, it is classical that  $f(L)$  is dense.

*Exercise.* Let  $M = n\text{-torus } \mathbb{T}^n = \mathbb{R}^n / \mathbb{Z}^n$

- covering map  $f: \mathbb{R}^n \rightarrow M$
- $L = \text{vector subspace of } \mathbb{R}^n$ .

Closure  $\overline{f(L)} = f(S)$  is a torus  $\mathbb{T}^k$  ( $\exists$  subspace  $S$  of  $\mathbb{R}^n$ ).

*The closure of  $f(L)$  is a very nice submanifold of  $M$ .*

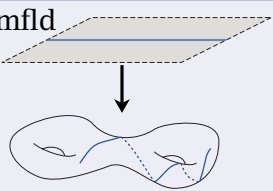
## Example in Riemannian geometry

### Example

Let  $M = \text{compact, hyperbolic } n\text{-mfld}$

- covering map  $f: \mathbb{H}^n \rightarrow M$
- line  $\mathbb{H}^1 \hookrightarrow \mathbb{H}^n$ .

Closure  $\overline{f(\mathbb{H}^1)}$  can be a fractal.



### Consequence of Ratner's Thm

$\mathbb{H}^2 \subset \mathbb{H}^n \implies \overline{f(\mathbb{H}^2)} = f(\mathbb{H}^k)$  is a submfld of  $M$   
 (immersed, maybe not embedded).  
 (Similar for other locally symmetric spaces.)

## Recall

- $f: \mathbb{R}^n \rightarrow \mathbb{R}^n / \mathbb{Z}^n$
  - $L = \text{vector subspace of } \mathbb{R}^n$
- $\implies \overline{f(L)} = f(S)$ ,  $\exists$  vector subspace  $S$  of  $\mathbb{R}^n$ .

- $\mathbb{R}^n$  is a Lie group.
- The subgroup  $\mathbb{Z}^n$  is a lattice.

## Generalization (Ratner's Theorem)

Replace:

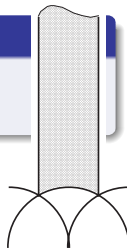
- $\mathbb{R}^n$  with any Lie group  $G$
- $\mathbb{Z}^n$  with any lattice  $\Gamma$  in  $G$
- $L$  with any subgroup of  $G$  that is generated by "unipotent" elements
- $S$  with a closed subgroup of  $G$

## Ideas in proof of Ratner's Theorem

### Example

$G = \text{SL}(2, \mathbb{R}) = \{ 2 \times 2 \text{ real mat's of det } 1 \}$ .  
 Let  $\Gamma = \text{SL}(2, \mathbb{Z})$ . Then  $\Gamma$  is a lattice in  $G$ .

Other choices of  $\Gamma$  can make  $G/\Gamma$  compact.



### Definition

Define  $u^t = \begin{bmatrix} 1 & t \\ 0 & 1 \end{bmatrix}$  and  $a^t = \begin{bmatrix} e^t & 0 \\ 0 & e^{-t} \end{bmatrix}$ .  
 Each is a homomorphism from  $\mathbb{R}$  to  $\text{SL}(2, \mathbb{R})$ .  
 $u^t$  is a **unipotent** one-parameter subgroup.

## Polynomial divergence

$$u^t = \begin{bmatrix} 1 & t \\ 0 & 1 \end{bmatrix} \quad \text{and} \quad a^t = \begin{bmatrix} e^t & 0 \\ 0 & e^{-t} \end{bmatrix}$$

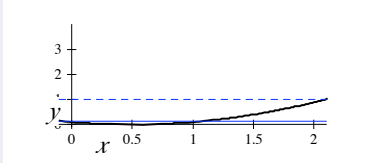


$$d(x, qx) = \|q\|. \quad d(u^t x, u^t qx) = \|u^t q u^{-t}\|.$$

$$u^t q u^{-t} = \begin{bmatrix} \alpha + \gamma t & \beta + (\delta - \alpha)t - \gamma t^2 \\ \gamma & \delta - \gamma t \end{bmatrix}$$

Points move apart at **polynomial speed**. (Slowly!)

## Points move apart at polynomial speed.

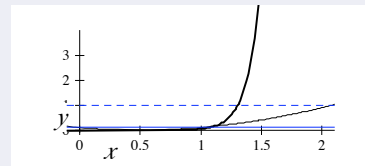


If 2 pts stay very close together for a length of time, then they stay close for just as long after that.

## Corollary

In a unipotent flow:  
if two points are very close together most of the time, then they are close together **all** of the time.

Contrast:  $a^t = \begin{bmatrix} e^t & 0 \\ 0 & e^{-t} \end{bmatrix}$   $a^t q a^{-t} = \begin{bmatrix} \alpha & \beta e^{2t} \\ \gamma e^{-2t} & \delta \end{bmatrix}$   
Points move apart at *exponential speed*.



## Fact

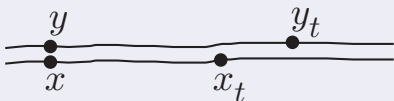
In a geodesic flow:  
2 points can be close together 99.999% of the time, and wander **independently** the rest of the time.

## Shearing

$$u^t = \begin{bmatrix} 1 & t \\ 0 & 1 \end{bmatrix}, u^t q u^{-t} = \begin{bmatrix} \alpha + \gamma t & \beta + (\delta - \alpha)t - \gamma t^2 \\ \gamma & \delta - \gamma t \end{bmatrix}$$

## Shearing

Fastest motion is parallel to the orbits.

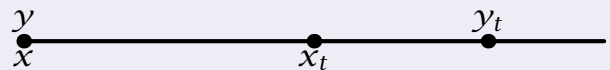


## Corollary

If  $x \approx y$ , then  $\exists t, y_t \approx x_{t+1}$ .

## Shearing

Fastest motion is parallel to the orbits.



Contrast:  $a^t q a^{-t} = \begin{bmatrix} \alpha & \beta e^{2t} \\ \gamma e^{-2t} & \delta \end{bmatrix}$   
Fastest motion is transverse to the orbits.



## Theorem (Ratner)

$$\begin{array}{ccc} \text{SL}(2, \mathbb{R})/\Gamma & \xrightarrow{f} & Z \quad \left( \begin{array}{l} \text{measurable,} \\ \text{not constant a.e.} \end{array} \right) \\ \downarrow u^t & & \downarrow \varphi_t \\ \text{SL}(2, \mathbb{R})/\Gamma & \xrightarrow{f} & Z \end{array} \Rightarrow f^{-1}(z) \text{ is countable a.e.}$$

*Pf.* Assume  $\varphi_1$  has no fixed pts (so  $d(\varphi_1(z), z) > \epsilon$ ) and  $f$  is uniformly continuous [Lusin's Thm].

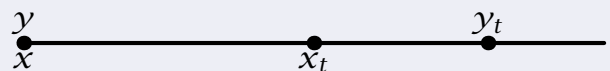
$f^{-1}(z)$  unctble  $\Rightarrow \exists x, y \in f^{-1}(z)$  with  $x \approx y$ .  
Flow along the orbits until  $d(x_t, y_t) = 1$ .



Then  $z_t = f(y_t) \approx f(x_{t+1}) = z_{t+1} = \varphi_1(z_t)$ .  $\rightarrow \leftarrow$

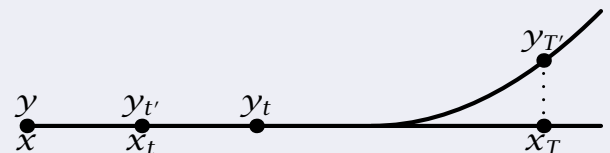
## Shearing

Fastest motion is parallel to the orbits.



## Key idea in Ratner's proof

Ignore motion along the orbit, and look at the *transverse* motion perpendicular to the orbit.



## Example

$$u^t = \begin{bmatrix} 1 & t \\ 0 & 1 \end{bmatrix}, u^t q u^{-t} = \begin{bmatrix} \alpha + yt & \beta + (\delta - \alpha)t - yt^2 \\ y & \delta - yt \end{bmatrix}$$

Fastest motion is along  $\{u^t\}$ .

Ignoring this, largest terms are diagonal (in  $\{a^t\}$ )

## Observation

$$a^t \begin{bmatrix} 1 & * \\ 0 & 1 \end{bmatrix} a^{-t} = \begin{bmatrix} 1 & * \\ 0 & 1 \end{bmatrix}: \quad a^t \text{ normalizes } \{u^t\}.$$

## Proposition

For action of a unipotent subgroup, the fastest transverse divergence is along the normalizer.

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## Application

If  $C$  is a min'l closed,  $u^t$ -inv't subset of  $G/\Gamma$ ,  
(and  $C$  not contained in a single  $N_G(\{u^t\})$ -orbit)  
then  $a^s C = C$ . (In fact,  $C = G/\Gamma$ .)

## Proof.

Choose  $x, y \in C$  with  $x \approx y$  and  $y \notin N_G(\{u^t\})x$ .  
Then  $u^{t_1}x \approx a^s u^{t_2}y$ .

Pretend  $u^{t_1}x = a^s u^{t_2}y \in C \cap a^s C \neq \emptyset$ .

But  $u^t a^s C = a^s u^t C = a^s C$ , so  $C \cap a^s C$  is  $u^t$ -inv't.  
Minimality:  $a^s C = C$ .  $\square$

## Ratner's Theorems

### Ratner's Theorem on Orbit Closures

$\overline{\{u^t\}x} = Sx$ ,  $\exists$  subgroup  $S$  of  $G$ .

### Ratner's Equidistribution Theorem

$\{u^t\}x$  is equidistributed in  $Sx$ :

$$\frac{1}{T} \int_0^T f(u^t x) dt \rightarrow \int_{Sx} f d\mu \quad \text{for } f \in C_c(G/\Gamma)$$

where  $\mu =$  (normalized)  $S$ -invariant volume form on  $Sx$ .

### Ratner's Measure-Classification Theorem

Any ergodic  $u^t$ -invariant probability measure on  $G/\Gamma$   
is (normalized)  $S$ -invariant volume form on  $Sx$   
for some subgroup  $S$  and some  $x \in G/\Gamma$ .

## Further reading

chapter of my forthcoming book on arithmetic grps

- free PDF file on my web page  
<http://people.uleth.ca/~dave.morris/books/IntroArithGroups.html>

my book: *Ratner's Theorems on Unipotent Flows*

- free PDF file on my web page (or the arxiv)  
<http://people.uleth.ca/~dave.morris/books/Ratner.html>

## Part 2: A Ratner Theorem Proof

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## Examples

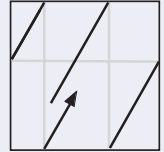
Let  $X = \text{torus } \mathbb{T}^2 = \mathbb{R}^2 / \mathbb{Z}^2$ .

Any  $v \in \mathbb{R}^2$  defines a flow on  $\mathbb{T}^2$ :

$$\varphi_t(x) = x + tv$$

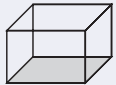
If the slope of  $v$  is irrational,  
 it is classical that every orbit is dense (& unif dist).

Also: Lebesgue is the only inv't probability measure.



$v = (a, b, 0)$  defines flow  $\varphi_t$  on  $\mathbb{T}^3 = \mathbb{R}^3 / \mathbb{Z}^3$   
 and  $\mathbb{T}^2 \times \{0\}$  is invariant.

Lebesgue on  $\mathbb{T}^2 \times \{0\}$  is an invariant measure.



$\forall v$ , any ergodic invariant probability meas for  $\varphi_t$  on  $\mathbb{T}^3$  is  
 Lebesgue meas on some subtorus  $\mathbb{T}^k$  ( $0 \leq k \leq 3$ ).

## Generalization

### Ratner's Measure-Classification Theorem

- $G = \text{Lie group}$
- $\Gamma = \text{lattice in } G$
- $u^t = \text{unipotent one-parameter subgrp of } G$
- $\mu = \text{ergodic } u^t\text{-inv't probability measure on } G/\Gamma$

$\Rightarrow \mu$  is (normalized)  $S$ -invariant volume form on  $Sx$   
 for some closed subgroup  $S$  and some  $x \in G/\Gamma$ .

Today:  $G = \text{SL}(2, \mathbb{R})$ .

Recall  $u^t = \begin{bmatrix} 1 & t \\ 0 & 1 \end{bmatrix}$  and  $a^s = \begin{bmatrix} e^s & 0 \\ 0 & e^{-s} \end{bmatrix}$ .

The volume on  $G/\Gamma$  is a finite, invariant measure.

### Theorem (Furstenberg)

$\text{SL}(2, \mathbb{R})/\Gamma$  compact  $\Rightarrow$  the only invariant probability  
 measure for  $u^t$  is the ordinary volume.

(In contrast,  $a^s$  has many invariant measures.)

### Corollary

Every  $u^t$ -orbit is uniformly distributed ( $\therefore$  dense).

### Theorem (Dani)

$\text{SL}(2, \mathbb{R})/\Gamma$  noncompact  $\Rightarrow$  other ergodic  $u^t$ -invariant  
 measure is the measure supported on a closed orbit.



## 1st step of the proof

### Recall (from transverse shearing)

If  $C$  is a minimal compact,  $u^t$ -inv't subset of  $G/\Gamma$ ,  
 (and  $C$  not contained in a single  $N_G(\{u^t\})$ -orbit)  
 then  $a^s C = C$ .

### Similar argument:

$a^s \mu = \mu$  (unless  $\mu$  is supported on a single  $N_G(\{u^t\})$ -orbit)

So we can use the dynamics of the  $a^s$ -flow:  
 entropy.

## 2nd step: entropy calculation

### Theorem (from Anne's lecture)

- $T = \text{vol-pres diffeo on manifold } M$  (cpct, smooth)
- tangent bundle  $\mathcal{T}M = \mathcal{E}_1 \oplus \dots \oplus \mathcal{E}_n$  ( $T$ -inv't),  
 $\forall \xi \in \mathcal{E}_i, \|T(\xi)\| = \tau_i \|\xi\|$ .

Then  $h_{\text{vol}}(T) = \sum_{\tau_i > 1} (\dim \mathcal{E}_i) \log \tau_i$ .

### Example (entropy of geodesic flow)

Recall  $a^s q a^{-s} = \begin{bmatrix} \alpha & \beta e^{2s} \\ \gamma e^{-2s} & \delta \end{bmatrix}$ .

$$\mathcal{T}M = \begin{bmatrix} 0 & * \\ 0 & 0 \end{bmatrix} \oplus \begin{bmatrix} * & 0 \\ 0 & * \end{bmatrix} \oplus \begin{bmatrix} 0 & 0 \\ * & 0 \end{bmatrix}.$$

So  $h_{\text{vol}}(a^s) = 2|s|$ .

Example.  $h_{\text{vol}}(a^s) = 2|s|$ .

### Proposition

Suppose  $\nu$  is  $a^s$ -inv't.  
Then  $h_\nu(a^s) \leq 2|s|$  with equality iff  $\nu$  is  $u^t$ -inv't.

### Corollary

$\mu$  is inv't under  $u^t$  and  $a^s \implies \mu = \text{Lebesgue}$ .

### Proof.

$\mu$  is  $u^t$ -inv't  $\implies h_\mu(a^s) = 2|s| \implies h_\mu(a^{-s}) = 2|s|$   
 $\implies \mu$  is invariant under  $\begin{bmatrix} 1 & 0 \\ r & 1 \end{bmatrix} = \nu^r$ .  
 $\mu$  is invariant under  $\langle u^t, a^s, \nu^r \rangle = \text{SL}(2, \mathbb{R})$ .  $\square$

## Prove $\mu$ is $a^s$ -invariant

We need to know a little bit about ergodicity.

**Definition.** Assume  $\mu = \varphi_t$ -inv't measure on  $X$ .  
 $\mu$  is ergodic for  $\varphi_t$ :  $\nexists \varphi_t$ -inv't measurable set  $C$  except  $\mu(C) = 0$  or  $\mu(C) = 1$ .

### Lemma

ergodic

$\iff \nexists$  nonconstant  $\varphi_t$ -invariant vector in  $L^2(X; \mu)$

$\iff \mu \neq \mu_1 + \mu_2$  unless  $\mu_1$  &  $\mu_2$  are scalar mults of  $\mu$

**Fact:** {convex combs of ergodic measures}  
 is dense in {invariant measures}.

### Remark

Howe-Moore Theorem implies  
 volume on  $G/\Gamma$  is ergodic for  $u^t$   
 (or any other closed, noncpt subgroup of  $G$ ).

If vol is ergodic for  $\varphi_t$ , then a.e.  $\varphi_t$ -orbit is dense.  
 In fact, the following fundamental theorem of  
 Ergodic Theory implies they are unif dist:

### Pointwise Ergodic Theorem

If  $\mu$  is ergodic for  $\varphi_t$ , and  $f \in L^1(\mu)$ , then  
 $\frac{1}{T} \int_0^T f(\varphi_t(x)) dt \rightarrow \int_X f d\mu$  for a.e.  $x \in X$ .

## Proof that $\mu$ is $a^s$ -invariant

Let  $\Omega = \{x \mid u^t\text{-orbit of } x \text{ is unif dist (w.r.t. } \mu)\}$   
 "generic set for  $\mu$ "

Pointwise Ergodic Theorem:  $\mu(\Omega) = 1$ .

Since  $a^s$  normalizes  $u^t$ , we know

- $a^s \mu$  is  $u^t$ -inv't (and ergodic), and
- $a^s \Omega$  is the generic set for  $a^s \mu$ .

Choose  $x, y \in \Omega$  with  $x \approx y$ . Then  $u^{t_1} x \approx a^s u^{t_2} y$ .

Pretend  $z = u^{t_1} x = a^s u^{t_2} y \in \Omega \cap a^s \Omega$ .

Orbit of  $z$  is equidistrib for both  $\mu$  and  $a^s \mu$ , so  $(\forall f)$

$\int_{G/\Gamma} f d\mu = \lim \frac{1}{T} \int_0^T f(u^t z) dt = \int_{G/\Gamma} f d(a^s \mu)$ ,  
 so  $\mu = a^s \mu$ .

We should not pretend that  $u^{t_1} x = a^s u^{t_2} y$ .

Suppose  $a^s \mu \neq \mu$ . Then (as above)  $\Omega \cap a^s \Omega = \emptyset$ .

Same is true for nearby values of  $s$

(because  $\{s' \in \mathbb{R} \mid a^{s'} \mu = \mu\}$  is closed).

Let  $K$  be a compact subset of  $\Omega$  with  $\mu(K) > 1 - \epsilon$ .

Then  $d\left(K, \bigcup_{s' \approx s} a^{s'} K\right) > \delta > 0$ .

Choose  $x, y \in \Omega$  with  $x \approx y$ . Then  $u^{t_1} x \approx a^{s'} u^{t_2} y$ .

By Pointwise Ergodic Theorem (and polynomial divergence) we may assume  $u^{t_1} x, u^{t_2} y \in K$ .

This contradicts the fact that  $d(K, a^{s'} K) > \delta$ .